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Azimuth Position

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Fixed field $e_m(t)$

Armature Gear Layout

Potentiometer $e_i(t)$

Desired azimuth angle

input Differential

amplifier and power

amplifier Motor

Schematic Desired

azimuth angle input

$e_i(t)$ n-turn

potentiometer 80 (t)

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Azimuth angle output

Differential

preamplifier Power

amplifier $v_p(t)$ $e_a(t)$

$V_i(t) + v_o(t) - k_g \text{ m}^2 \text{ N-}$

$\text{m s/rad V-s/rad N-m/A}$

$n \dots$

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Polytechnic University, Pomona. In addition to being the author of Control Systems Engineering, Professor Nise has contributed to the CRC publications The Engineering Handbook, The Control Handbook, and The Electrical Engineering Handbook.

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